

#### Innovations in Engineering



## Micro/Macro Integration of Nanostructures and Nanomaterials

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## The Charles Stark Draper Laboratory, Inc.

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**Applied research and development Technology transfer** Advanced technical education Divested from MIT in 1973 Headquarters in Cambridge, Mass. Site offices in Houston; Huntsville; Tampa Bay; and Washington, D.C. Revenues exceed \$420 million Approximately 1400 employees 65% technical staff <sup>2</sup>/<sub>3</sub> with advanced degrees



Photo credit: John Earle



#### **Draper's Evolution**

#### From the Birthplace of Inertial Navigation to Advanced Engineering R&D



**Guidance, Navigation & Control** 







**Microsystems** 



Autonomous Systems



Distributed Communications & Control



**Critical System Design** 



# Vanishingly Small Systems



Sensors DSP in FPGA Large Value Passives Mixed Signal and Structured ASICs Thermal Management High Efficiency RF PA Algorithms i-UHD Electronics Packaging Frequency Reference RF MEMs Antennas Power Source Waveforms/Protocols

Bottom Bump Lav





- Mainly in MEMS and Biomedical Areas (some robotics)
- Typically, nanostructured element or nanomaterials integrated with MEMS device or other micro/macro system
- Extensive interactions/collaborations with universities
- Areas:
  - Nanostructured polymers
    - tissue engineering, gecko adhesion
  - Nanostructured metal films
    - chem/bio sensors
  - CNT integration with MEMS

- Applications: rotary MEMS (*e.g.* gyroscope, ...)





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# **Nanostructured Polymers**







# **Typical process**



#### Feature sizes: few microns $\rightarrow$ ~50 nm

optical contact litho (~400 nm), e-beam litho, interference litho, diblock copolymers, ...
*n.b.* shown below are ~800 nm feautures, but exploring finer topography as well
Molds: Si, SiO<sub>2</sub>, electroplated Ni, ...
Wide variety of polymers
Also investigated injection nanomolding with Si inserts



## **Tissue Engineering**

- Long-term goal: Micro/nanotopography to cue stem cell growth/behavior for proper function as replacements in existing organs and/or in artificially-engineered organs
  - *e.g.* **retinal cells** for macular degeneration, retinitis pigmentosa
  - *e.g.* **renal tubule cells** for kidney disease
- Current Research: Create synthetic cellular environments to attempt to replicate native environment of cells
  - Investigate cell type-specific responses, such as alignment, elongation and cell-cell junction formation in a physiologically realistic environment
  - Contribute to research surrounding cellular superstructure formations and stem cell differentiation as well as to the evergrowing fields of tissue engineering and regenerative medicine





## Retinal stem cells cultured on polycaprolactone thin film

- -Thin for subretinal transplantation (<10um)
- -Can deliver large population of cells
- -Provide cell guidance with submicron cues
- -Relatively stiff for surgical manipulation
- -Flexible for curvature
- -Biocompatible/biodegradable in sub-retinal space







### Retinal stem cell morphology response to micro/nano features









# **Kidney tubule cell culture**

Flat PS

**Patterned PS** 



- Human renal proximal tubule cells
- Ridge-groove features horizontal (red arrows)
  - 0.9-1.0 µm in width.
- Cells align and elongate only on the patterned PS
- All scale bars 50 µm



# Nanopatterned Artificial Gecko Adhesive

#### Biomimetic adhesive (one-sided velcro)



# 2 million setae per gecko

#### Gecko adhesion:

- Millions of tiny (~200 nm) spatulae
- Spatulae adhere by van der Waals forces
- Adheres to a variety of surfaces, wet/dry, etc.

#### Artificial gecko adhesive fabrication:

- Use nanolithography to pattern nanomolds
- Mold and release polymers



#### Biomimetic material adheres better than gecko





# **Gecko-based Medical Adhesive**

- •Fabricate micro/nanostructures of biodegradable polymers
- Functionalize surfaces of structures to improve adhesion to tissue
- •Test adhesion to tissue (porcine intestines)
- Implant into rats and observe inflammation response (~none)

Potential application to wound sealing, augmenting surgical sutures or staples





2008). DRAPER 🔘

A biodegradable and biocompatible gecko-inspired tissue adhesive, A. Mahdavi et al, PNAS 105 2307 (2008).

## **Biomimetic Adhesion (DARPA Zman)**



The inspiration for these climbing aids is the technique by which geckos, spiders, and small animals scale vertical surfaces, that is, by using unique biological material systems that enable controllable adhesion using van der Waals forces or by hooking surface asperities.

Human Hair 50 µm



Insect microspine: Hook into small asperities on surface

adenovirus

Gecko adhesion:

Millions of tiny (~200 nm) spatulae adhere by van der Waals forces. The support structure ensures intimate contact between spatulae and surface.

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# **Nanostructured Metal Films**





#### **Plasmonics Phenomena and Applications**

#### Plasmonic nanoantenna

- DNA Sensor
- Extraordinary Optical Transmission (EOT)
  - Biosensor/Calorimeter









## **Direct Linear Analysis (DNA detection)**





## Single Molecule $\rightarrow$ no PCR





#### **Fabrication**





## Testing



#### Channel filled with dye solution - Arc lamp illumination



### Channel filled with dye solution - Laser input

Plasmonic resonance exciting fluorophores



#### **Principle of Nanohole Array Biosensing System**





## **Possibly next generation of SPR**



#### Potential Applications: Binding Assays: Multiplex detection of cancer biomarkers Protein array Calorimetry





## Multiplexed sensing with nanohole references

Sensor performance can be tailored







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# **MWNT Integration with MEMS**





### Micro & Nano Bearings





#### 1988, Bell Labs

#### ~2006, Sandia

Other approaches: air bearing (MIT), ball bearings (Maryland)...

Rotational microdevices still only in limited applications (*e.g.* Sandia safe and arm)

WHY? Reliability, lifetime, complexity, speed, wobble



## **Inspiration: Previous Rotating CNT Bearing Devices**



A.M. Fennimore *et. al*, Nature 424, 408 (2003)
John Cumings and A. Zettl, *Science* 289, 602 (2000).



A. Zettl, et al., U.C. Berkeley. Retrieved from: http://www.physics.berkeley.edu/ research/zettl/projects/Rotorpics.html

#### Two groups have made "see-saw" like flipper devices

(Zettl @ Berkeley, Bourlon @ École Normale Supérieure)

#### Accomplishments:

- Demonstrated CNT rotary bearings
- Demonstrated Electrostatic Motor
- Demonstrated long term, reliable operation
- Noted lack of wear
- One rotary static friction measurement



2. Bertrand Bourlon et. al, Nano Letters 4, 709 (2004)

#### Areas for Improvement:

Used Horizontal Tube  $\rightarrow$  no axisymmetry possible

Axisymmetry would: improve rotor balance increase speed capabi enable superior electro

improve rotor balance increase speed capability enable superior electrostatics enable more complex geometries

Tubes randomly distributed  $\rightarrow$  no batch fabrication

No dynamic friction measurements



### **Draper Approach – Vertical Tube Orientation**

#### Enables: axisymmetric design

→superior rotor balancing, electrodes, turbine blades, etc.



## **Device Rotordynamic Model**

**Stodola Rotor – well established dynamics** 

- 5 degrees of freedom
- Rigid thin disk, Euler simple beam shaft

**Predicts:** 

- Natural & critical speeds,
- Angular and lateral displacements induced by imbalance
- Beam stresses







### **Molecular Dynamics Simulations**

Simulation literature (without suspect papers) gives about 2-3 orders variation in MWNT friction







## **CNT/MEMS Process Compatibility**

		Process	Com- patible	SEM	TEM	Notes	Other Refs	Process Parameters
	c	PECVD oxide	ves	x	x	Few or no defects introduced. Conformal, uniform coating. 5-10 nm layer close to tube may have altered	2,3	22 sccm SiH <sub>4</sub> , 750 sccm N <sub>2</sub> O, 430 sccm N <sub>2</sub> , 1800 mTorr, 20W, 380°C, 30 sec
	itio	PECVD nitride	ves	x	x	Few or no defects are introduced by PECVD. Coating is conformal, uniform.	4,5	20 sccm SiH <sub>4</sub> , 20 sccm NH <sub>3</sub> , 1000 sccm N <sub>2</sub> , 650 mTorr, 20 W (7 sec @ kHz, 14 sec @ MHz cycles) 380° C 2 min
	bos	LPCVD poly-silicon	yes		x	No defects are introduced by LPCVD. Coating is not uniform (for thin coating); nucleates into poly-crystals.		80 sccm SiH <sub>4</sub> , 150 mTorr, 585° C, 5 min
	De	PECVD amorph-Si	ok		x	Some defects are introduced by PECVD. Coating is conformal, uniform.	6	50 sccm SiH <sub>4</sub> , 1950 mTorr, 9W, 380°C, 2 min
Etch		piranha	yes	х		Very little or no bulk damage to poorly graphitized tubes.		3 H <sub>2</sub> SO <sub>4</sub> : 1 H <sub>2</sub> O <sub>2</sub> (30%), 30 min, room temperature
		RCA SC1	ok	х	x	Did not cause much bulk damage. 1-2 outer layers may suffer slight damage. Poorly graphitized tubes showed little or no bulk damage.		5 H <sub>2</sub> O: 1 NH <sub>4</sub> OH: 1 H <sub>2</sub> O <sub>2</sub> (30%), 30 min, room temperature
		кон	ok	х	x	Slowly introduces substantial defects at outer walls, but few defects deep within the tube. Poorly graphitized tubes showed small bulk etching.	7,8,9	45% KOH, 80°C, 30 min
	et	dilute aqua regia	ok	x		Very little or no bulk damage to poorly graphitized tubes. Aqua regia appears to have attacked the catalyst.	10	2 H $_2$ O : 1 HNO $_3$ (50-70%): 3 HCl (35%), 30 min, room temperature
	3	isopropanol	yes	x	x	lsopropanol was used for all wet etch runs, which were dried via a critical point dryer. Some of these were compatible, so Isopropanol must also be completely compatible.		30 min (required for critical point drying)
		acetone	yes	x		Very little or no bulk damage to poorly graphitized tubes.	11,12	12 hours, room temperature
		dilute nitric acid	ok	х		Very little or no bulk damage to poorly graphitized tubes. May attack catalyst.	13,14	4 H <sub>2</sub> O: 1 HNO <sub>3</sub> (50-70%), 30 min, room temperature
		liquid buffered HF	yes	x	x	BHF does not cause bulk damage to even poorly graphitized tubes. Strips oxide from tube, except for thin layer.	15-17	35% NH <sub>4</sub> F, 6.25% HF, 58.75% H <sub>2</sub> O, 30 min, room temperature
		vapor HF	yes	x		Very little or no bulk damage to poorly graphitized tubes.		40°C, over dish of 49% HF, 30 min
		XeF <sub>2</sub>	yes		x	XeF <sub>2</sub> causes no damage at all to highly graphitized nanotubes, and little or no visible damage to CVD tubes. It may cause catalyst swelling, or removal of some outer layers of amorphous carbon.		25 cycles of 1 min exposure to XeF <sub>2</sub> gas
		SF <sub>6</sub> + O <sub>2</sub> RIE (cryo)	ok	х		May strip some outer layers of (probably amorphous) material from poorly graphitized tubes, yielding "match-sticks" with catalyst heads.		50 sccm SF <sub>5</sub> , 10 sccm O <sub>2</sub> , 60 mTorr, 100W, 30 min, -25°C
		Ar RIE	no	x		Severe damage or polymerization after long etch. Sharpens tube, causes significant bending.	18	30 sccm Ar, 60 mTorr, 100W, 30 min, room temperature
		SF <sub>6</sub> RIE	no	x		Severe damage or polymerization after long etch. Sharpens tube, causes significant bending.		60 sccm SF <sub>6</sub> , 60 mTorr, 100W, 30 min, room temperature
	2	$SF_6 + O_2 RIE$	no	x		Severe damage or polymerization after long etch. Sharpens tube, causes significant bending.		60 sccm SF <sub>6</sub> , 10 sccm $O_2$ , 60 mTorr, 100W, 30 min, room temperature
	ō	CF <sub>4</sub> RIE	no	x		Severe damage or polymerization after long etch. Sharpens tube, causes significant bending.		25 sccm CF <sub>4</sub> , 60 mTorr, 100W, 30 min, room temperture
		$CF_4 + O_2 RIE$	no	х		Causes etching at the tip, possibly just due to sputtering (as it is uniform across etch chemistries). Sharpens tube.	5	25 sccm CF <sub>4</sub> , 5 sccm O <sub>2</sub> , 60 mTorr, 100W, 30 min, room temperature
		DRIE	yes	x		Non-aggressive recipe; little or no bulk damage to poorly graphitized tubes.		Etch cycle: (130 sccm SF <sub>6</sub> , 13 sccm O <sub>2</sub> , 20 mTorr, 150W ICP, 22W platen, 8 sec) Passivation cycle: (100 sccm C <sub>4</sub> F <sub>8</sub> , 20 mTorr, 600W ICP, 22W platen, 5 sec) Overall: (16 cycles, 2:48 minutes)
		$CHF_3 + CF_4 RIE$	no	x		Causes etching at the tip, possibly just due to sputtering (as it is uniform across etch chemistries). Sharpens tube, causes significant bending.		14.6 sccm CHF <sub>3</sub> , 1.4 sscm CF <sub>4</sub> , 20 mTorr, 200W, 30 min, room temperature
		O <sub>2</sub> plasma RIE					19	30 sccm O <sub>2</sub> , 60 mTorr, 100W, 30 min, room temperature
		O₂ plasma ash	no	x	x	Oxygen plasma attacks amorphous carbon strongly, and nanotube walls slowly. Poorly graphitized tubes are strongly damaged. Well graphitized tubes are undamaged.	17	40 sccm O <sub>2</sub> , 200 mTorr, 55W, 30 min, room temperature



# **Status**

#### **Device Fabrication Demonstrated**



CVD nanotube quality inadequate for rotation (also true for COTS nanotubes)

- Built chamber and optimizing arc-deposition process
- Investigating pick-and-place in FIB/nanomanupilator
- Possibly electrophoretic placement



# **MWNTs**



#### **COTS Graphitized MWNTs**





Locally: good crystallinity, no amorphous carbon Larger-scale: defects (bamboo, kinks, chevrons, etc.)

#### Arc-Grown CNTs w/ pick-and-place







### Thoughts on Challenges and Opportunities for Integrated Nanosystems

- Microfab/top-down nanofab bootstraps from the semiconductor industry
  - Very good at planar fabrication
- May not want nanostructures/materials to be planar for best utilization
  - MWNT Bearing offers advantages to going perpendicular to the substrate (~2.5D?)
  - Most surface plasmon structures are 2-D (maybe 2.5D)
    - 3-D could offer optical metamaterials, optical cloaking devices, etc.
  - Biology is not planar; nano-bio interface offers huge rewards
  - How to fabricate 3D nano/micro structures and interface them with macro structures
- Best nanostructures may be produced in a messy batch process
  - e.g. Arc-deposited MWNTs
  - Techniques to precisely sort/place nanostructures/mat'ls onto/into 2D/3D structures

#### • Multiscale/multimode simulation to fully understand structures and interactions

- Spanning from molecular interactions potentially to meters
- e.g. To model gecko: 8 o.o.m. in size (mechanical structures): VdW w/surface, ~100 nm spatulae, ~10100 um setae, few-mm toes, ~cm paws, ~10 cm body
- Fault-tolerant design for nano/micro/macrosystems
  - Self-assembly will have defects (thermodynamics)
  - Need electrical, mechanical designs that can deal with those defects
    - Computation, biosensor, gecko adhesive support structure, etc.

